

(2-H DOT OR LINE INVERSION METHOD)

time HSYN (G4) (2-H DOT OR LINE INVERSION METHOD) = X THSYN (G3) ≥**≬** THSYN (G2) **-**™ _ ₹ THSYN (G1) **≥λ** VOE-SOURCE DRIVER -OUTUPT FIG. 2 PRIOR ART

FIG. 3 PRIOR ART

(DOT INVERSION METHOD)

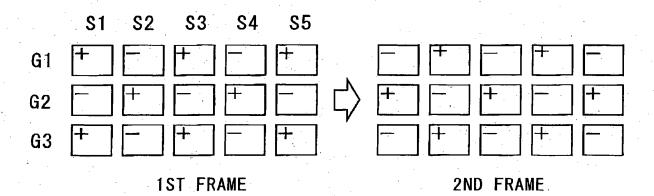


FIG. 4 PRIOR ART

(2-H DOT INVERSION METHOD)

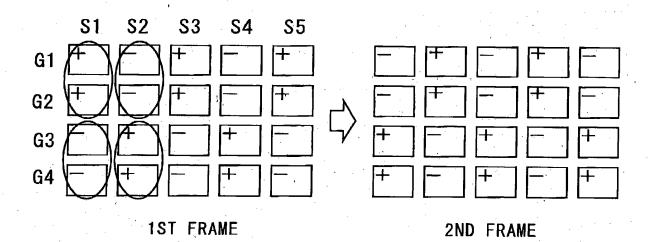
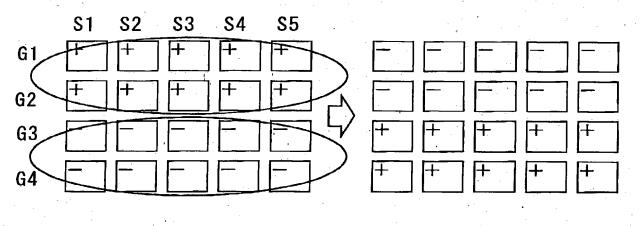


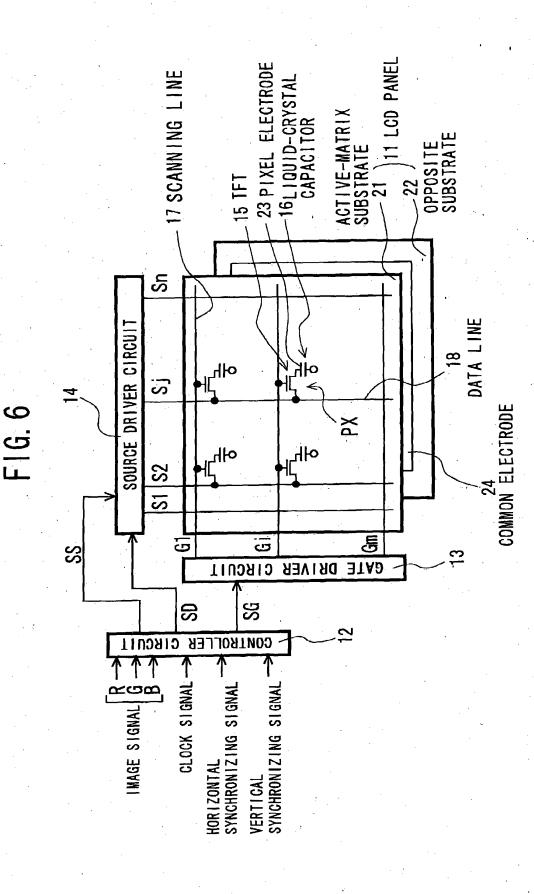
FIG. 5 PRIOR ART

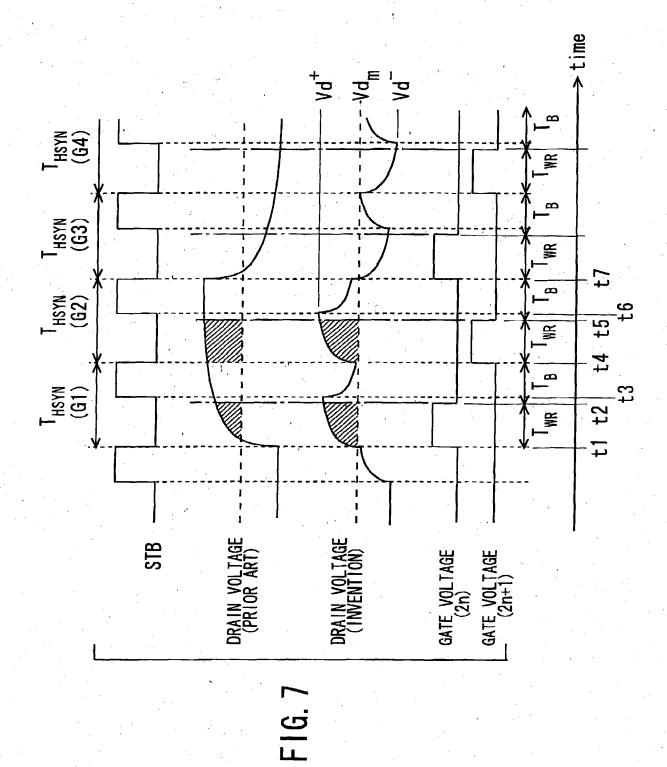
(2-H LINE INVERSION METHOD)

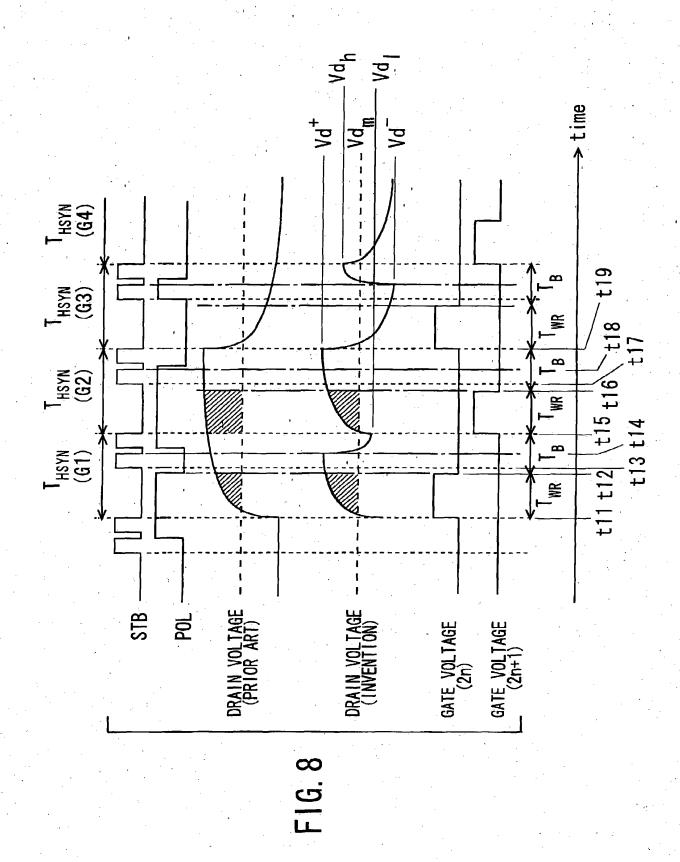


1ST FRAME

2ND FRAME







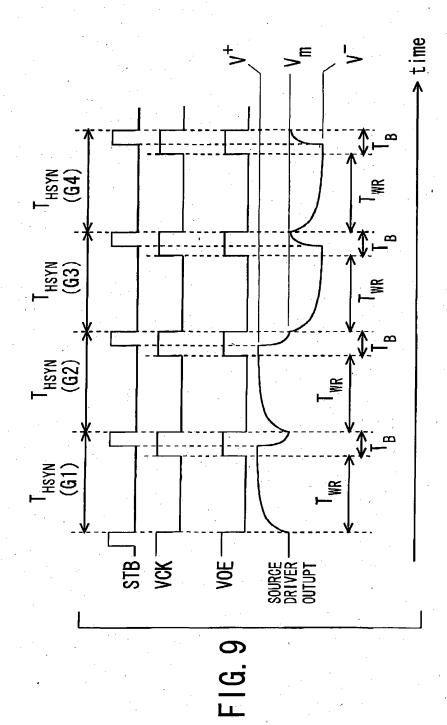


FIG. 10

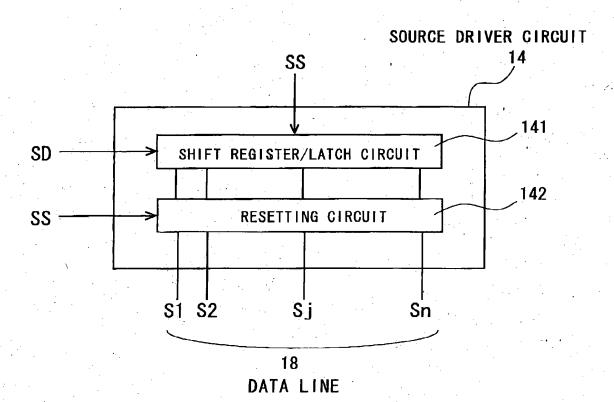


FIG. 11

